Knuth-Morris-Pratt Algorithm

CS181 Fall 2020

Overview of Knuth-Morris-Pratt (KMP)

- The Knuth-Morris-Pratt (KMP) algorithm is a pattern-matching algorithm; it finds all occurrences of a pattern P of length p in a text T of length t
- It takes advantage of the failure function f on the pattern P to search in linear time O(p + t)!
 - The general idea is that after we've seen a character in T once, we should already be able to tell whether the pattern could start there, even if we never explicitly attempted to match P_1 directly to T_j
- We've already seen the algorithm and pseudocode for constructing the failure function, so we'll focus on KMP here using a similar example

Definitions

- Inputs:
 - \circ Text T, indexed by j from 1 to t
 - Pattern *P*, indexed by *i* from 1 to *p*
- Output:
 - A list of positions k, where $T_{k:k+p} = P$
- Failure function, f
 - \circ A table of p entries, where each entry f(i) is the length of the longest proper suffix of $P_{1:i}$ which is also a proper prefix of P
 - See previous slide deck for a more detailed explanation

The Algorithm

- Calculate the failure function f for the pattern P
- Construct a skeleton DFA which accepts P and includes transitions based on f
- 3. Initialize the skeleton DFA to state 0 and the *T* pointer to 1
- 4. Iterate through the text *T*

**Here we show a version of the pseudocode which conceptualizes KMP with an accepting skeleton DFA. In practice, the skeleton DFA behavior can also be achieved using only the pattern P, the failure function f, and a pointer i which indexes symbols in P rather than states in M.

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
j \leftarrow 1
while j \leq t do
   if T_i = P_{i+1} then
        j \leftarrow j + 1
        M enters state M_{i+1}
        if M is in state M_p then
            record (j-p)
            M enters state M_{f(p)}
        end
   else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        end
   \mathbf{end}
end
```

An Example

```
T = aabbabaabaabca
P = abaabc
```

```
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end
```

i	1	2	3	4	5	6
P_{i}	а	b	а	а	b	С
f(i)	0	0	1	1	2	0

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       \mathbf{end}
    end
end
```

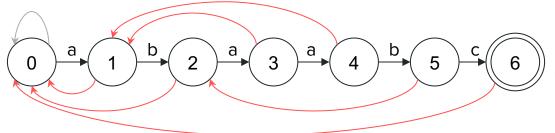
^{**}See previous set of slides for exactly how we constructed this!

i	1	2	3	4	5	6
P_i	a	b	а	а	b	С
f(i)	0	0	1	1	2	0

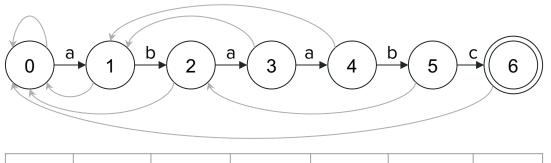
```
0 \xrightarrow{a} 1 \xrightarrow{b} 2 \xrightarrow{a} 3 \xrightarrow{a} 4 \xrightarrow{b} 5 \xrightarrow{c} 6
```

```
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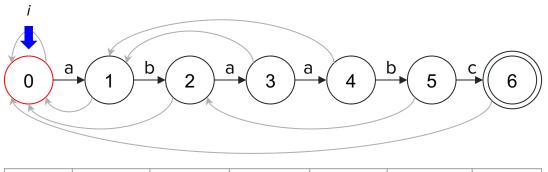
f(i)

0

0

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end
```

j •



```
f(i) 0 0 1 1 2 0
```

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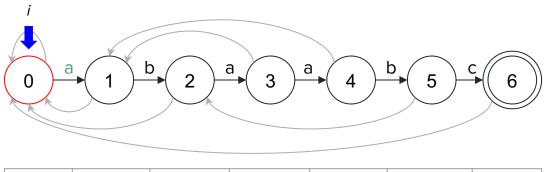
j

f(i)

0

0

aabbabaabaabca abaabc



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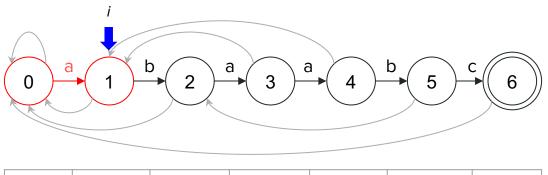
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0

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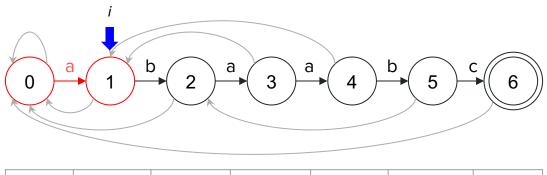
j ↓

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0

0

aabbabaabaabca abaabc



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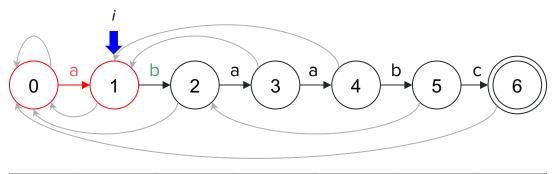
j •

f(i)

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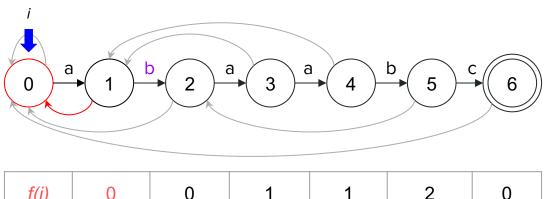
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2

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end
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calculate f(i) for $1 \le i \le p$



0

f(i)

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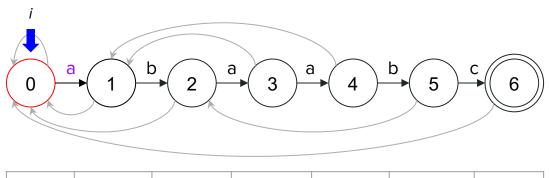
j •

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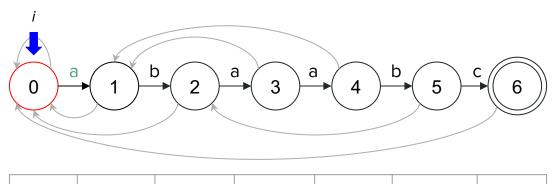
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f(i)

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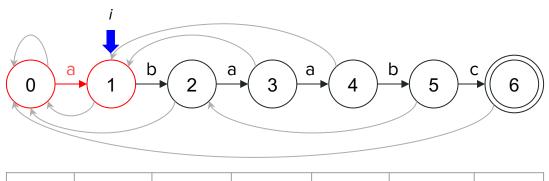
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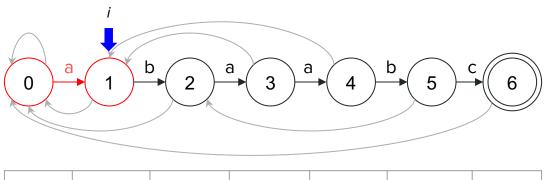


f(i)

0

0

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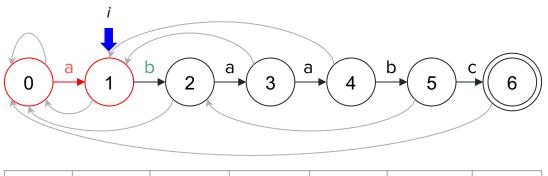


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0

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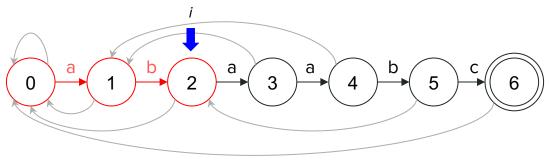
j

f(i)

0

0

aabbabaabaabca abaabc



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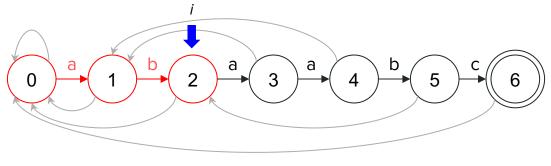
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0

aabbabaabaabca abaabc



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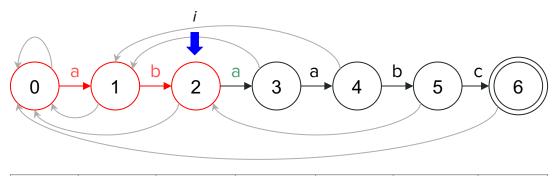
j I

f(i)

0

0

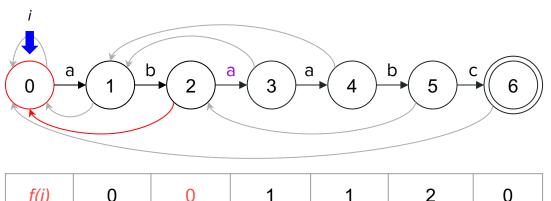
aabbabaabaabca abaabc



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```

calculate f(i) for $1 \le i \le p$



f(i)

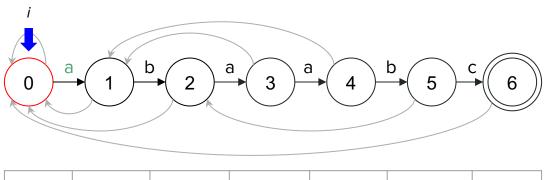
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0

0

aabbabaabaabca abaabc



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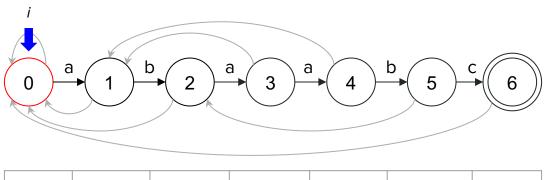
j

f(i)

0

0

aabbabaabaabca abaabc



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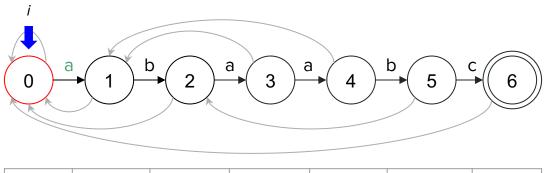
j

f(i)

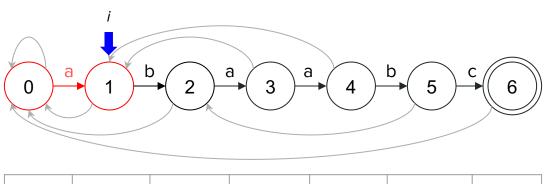
0

0

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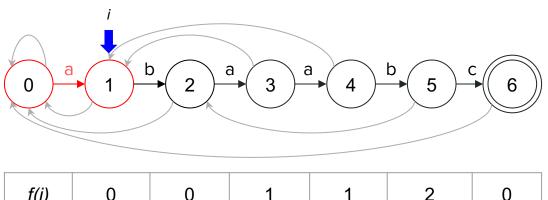


f(i)

0

0

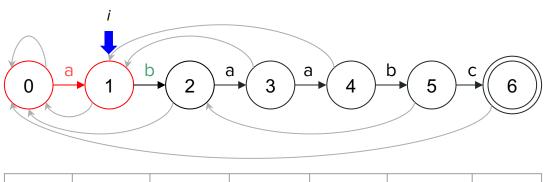
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        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```



f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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j \leftarrow 1
while j \leq t do
    if T_j = P_{i+1} then
        j \leftarrow j + 1
        M enters state M_{i+1}
        if M is in state M_p then
            record (j-p)
            M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```



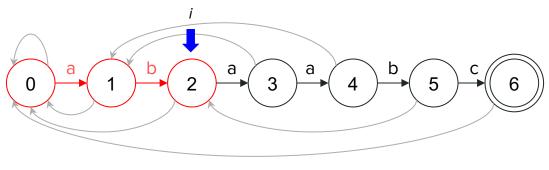
f(i)

0

0

```
calculate f(i) for 1 \le i \le p
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             M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

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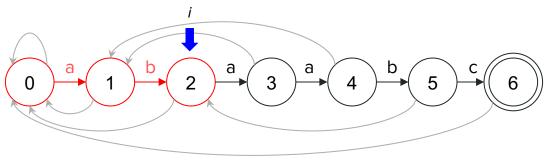
f(i)

0

0

```
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        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```

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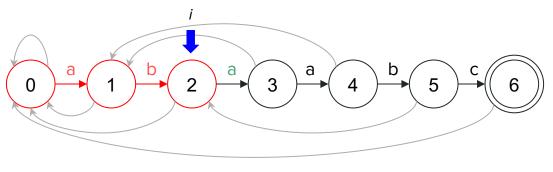
f(i)

0

0

```
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        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

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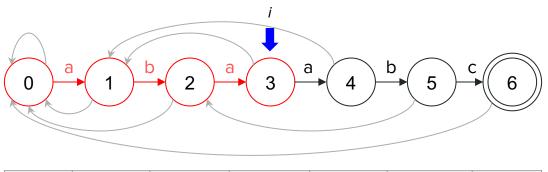
f(i)

0

0

```
calculate f(i) for 1 \le i \le p
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               record (j-p)
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          end
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          if M is in state M_0 and T_i \neq P_{i+1} then
               j \leftarrow j + 1
          \mathbf{end}
     \mathbf{end}
\mathbf{end}
```

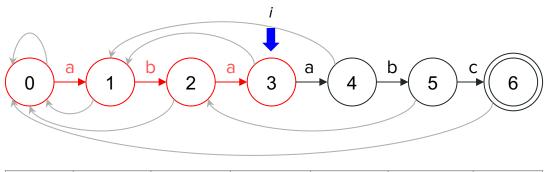
j •



```
f(i) 0 0 1 1 2 0
```

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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            M enters state M_{f(p)}
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        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```

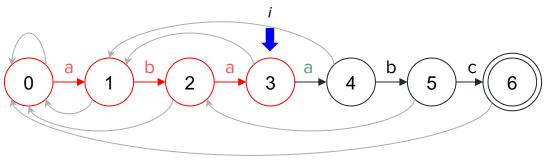
j •



```
f(i) 0 0 1 1 2 0
```

```
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            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
\mathbf{end}
```

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f(i)

0

0

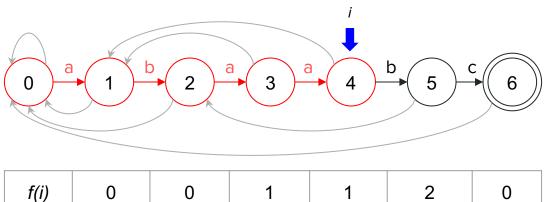
2

0

```
construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
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               M enters state M_{f(p)}
          end
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          M enters state M_{f(i)}
          if M is in state M_0 and T_i \neq P_{i+1} then
               j \leftarrow j + 1
         \mathbf{end}
    \mathbf{end}
end
```

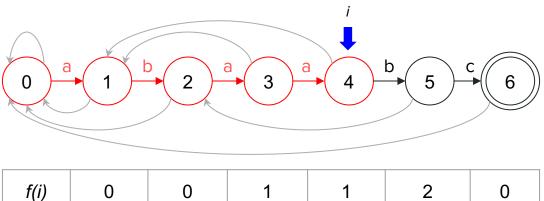
calculate f(i) for $1 \le i \le p$

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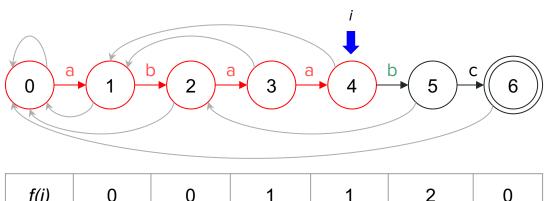
```
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        \mathbf{end}
   \mathbf{end}
end
```

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```
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            M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
end
```

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0

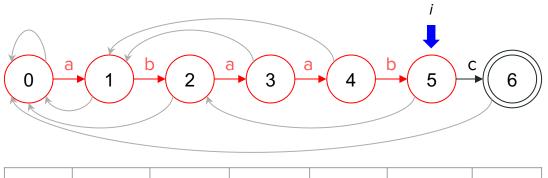
f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

2

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f(i)

0

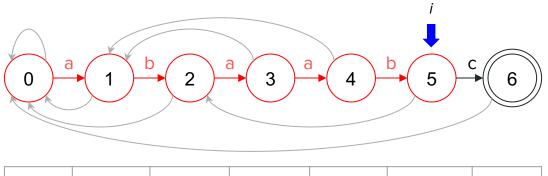
```
calculate f(i) for 1 \le i \le p
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        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```

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f(i)

0

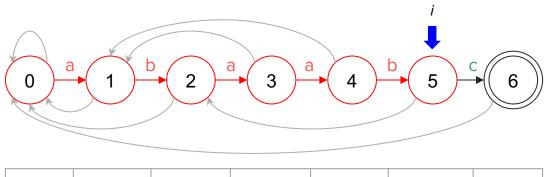
```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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        end
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        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
end
```

J I

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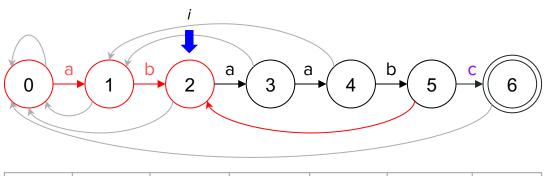


f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
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        if M is in state M_p then
            record (j-p)
             M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

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0

f(i)

0

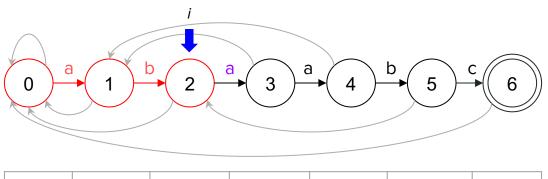
```
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
j \leftarrow 1
while j \leq t do
     \underbrace{\begin{array}{c} \textbf{if } T_j = P_{i+1} \\ \mid j \leftarrow j+1 \end{array}} \textbf{then}
           M enters state M_{i+1}
          if M is in state M_p then
                record (j-p)
                M enters state M_{f(p)}
          end
     else
           M enters state M_{f(i)}
          if M is in state M_0 and T_i \neq P_{i+1} then
                j \leftarrow j + 1
          \mathbf{end}
     \mathbf{end}
\mathbf{end}
```

construct a skeleton DFA M for P using f

calculate f(i) for $1 \le i \le p$

2

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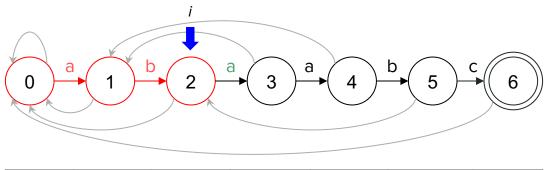
f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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        if M is in state M_0 and T_j \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
\mathbf{end}
```

j ↓

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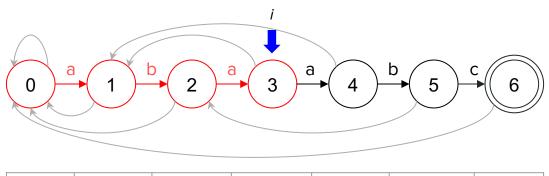


```
f(i) 0 0 1 1 2 0
```

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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        if M is in state M_0 and T_i \neq P_{i+1} then
             j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
\mathbf{end}
```

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f(i)

0

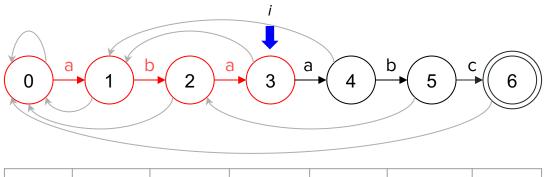
0

```
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            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```

calculate f(i) for $1 \le i \le p$

2

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f(i)

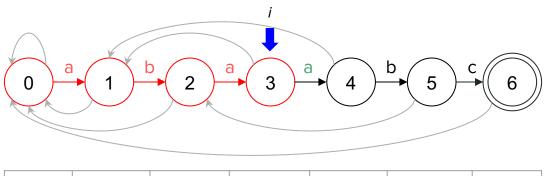
0

```
calculate f(i) for 1 \le i \le p
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            j \leftarrow j + 1
        \mathbf{end}
    end
\mathbf{end}
```

j

2

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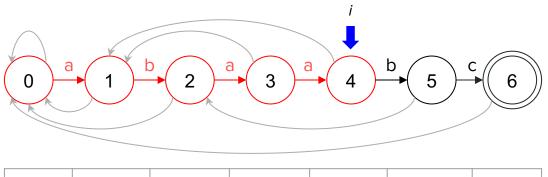
f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
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            j \leftarrow j + 1
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    end
end
```

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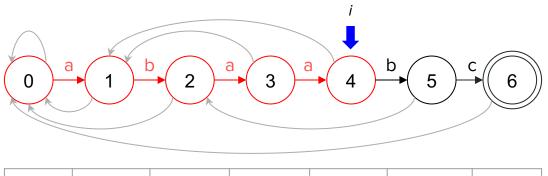
f(i)

0

```
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           j \leftarrow j + 1
       \mathbf{end}
    end
end
```

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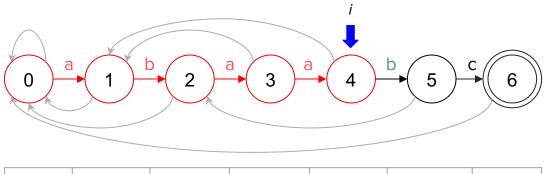
f(i)

0

```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
end
```

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f(i)

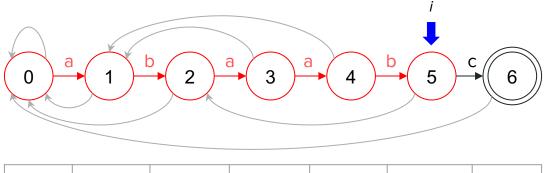
0

```
calculate f(i) for 1 \le i \le p
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```

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0

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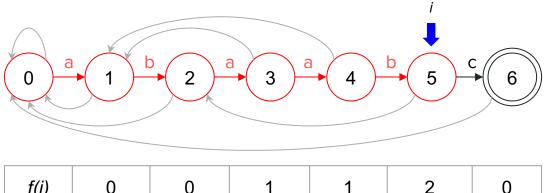


f(i)

0

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end
```

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f(i)

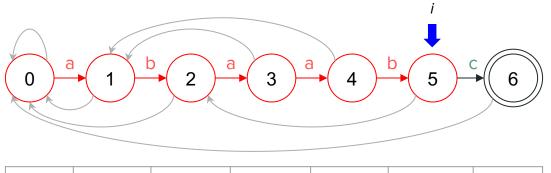
0

```
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```

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0

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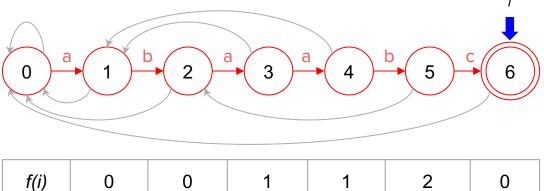


f(i)

0

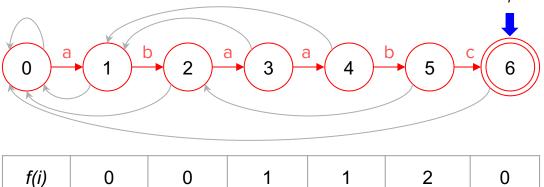
```
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    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

aabbabaabaabca abaabc



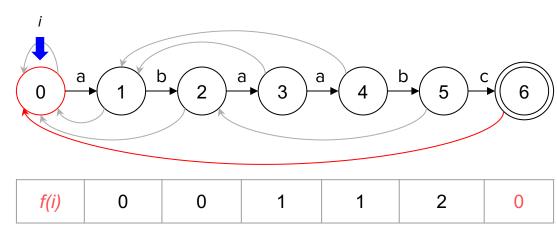
```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
j \leftarrow 1
while j \leq t do
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        M enters state M_{i+1}
        if M is in state M_p then
            record (j-p)
            M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
   \mathbf{end}
end
```

aabbabaabca abaabc



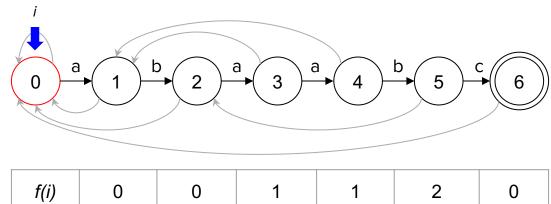
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        j \leftarrow j + 1
        M enters state M_{i+1}
        if M is in state M_p then
            record (j-p)
            M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

aabbabaabaabca abaabc



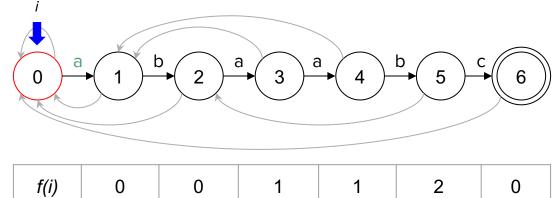
```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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j \leftarrow 1
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        j \leftarrow j + 1
        M enters state M_{i+1}
        if M is in state M_p then
            record (j-p)
            M enters state M_{f(p)}
        end
    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
end
```

aabbabaabaabca



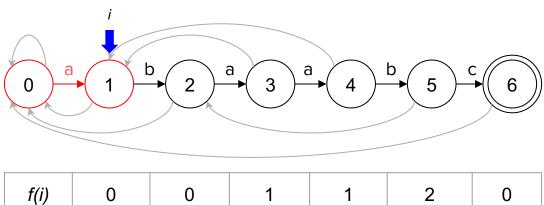
```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
j \leftarrow 1
while j \leq t \ \mathbf{do}
    \begin{array}{ll} \textbf{if} \ T_j = P_{i+1} \, \textbf{then} \\ | \ j \leftarrow j+1 \end{array}
         M enters state M_{i+1}
         if M is in state M_p then
              record (j-p)
              M enters state M_{f(p)}
          end
     else
          M enters state M_{f(i)}
         if M is in state M_0 and T_i \neq P_{i+1} then
              j \leftarrow j + 1
         \mathbf{end}
     end
end
```

aabbabaabaabca



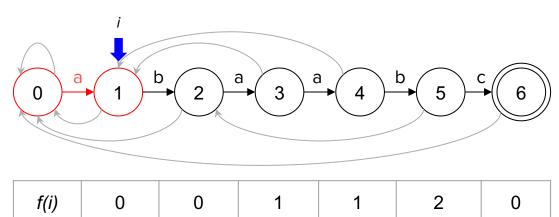
```
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construct a skeleton DFA M for P using f
M starts in state M_0
i := \text{current state in } M \text{ (updated with transitions)}
j \leftarrow 1
while j \leq t do
    \underbrace{\begin{array}{c} \mathbf{if} \ T_j = P_{i+1} \\ | \ j \leftarrow j+1 \end{array}}_{} \mathbf{then}
          M enters state M_{i+1}
         if M is in state M_p then
              record (j-p)
              M enters state M_{f(p)}
         end
     else
          M enters state M_{f(i)}
         if M is in state M_0 and T_i \neq P_{i+1} then
              j \leftarrow j + 1
         \mathbf{end}
     end
end
```

aabbabaabaabca



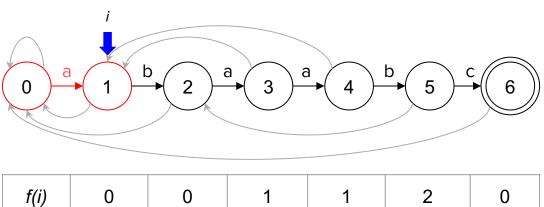
```
calculate f(i) for 1 \le i \le p
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        M enters state M_{i+1}
        if M is in state M_p then
             record (j-p)
             M enters state M_{f(p)}
        end
    else
         M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
\mathbf{end}
```

aabbabaabaabca



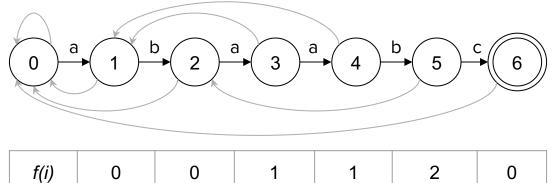
```
calculate f(i) for 1 \le i \le p
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M starts in state M_0
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j \leftarrow 1
while j \leq t \ \mathbf{do}
    \begin{array}{ll} \textbf{if} \ T_j = P_{i+1} \, \textbf{then} \\ | \ j \leftarrow j+1 \end{array}
          M enters state M_{i+1}
         if M is in state M_p then
              record (j-p)
              M enters state M_{f(p)}
         end
     else
          M enters state M_{f(i)}
         if M is in state M_0 and T_i \neq P_{i+1} then
              j \leftarrow j + 1
         \mathbf{end}
     end
end
```

aabbabaabaabca



```
calculate f(i) for 1 \le i \le p
construct a skeleton DFA M for P using f
M starts in state M_0
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while j \leq t do
        M enters state M_{i+1}
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            record (j-p)
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    else
        M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
            j \leftarrow j + 1
        \mathbf{end}
    end
\mathbf{end}
```

aabbabaabaabca



```
calculate f(i) for 1 \le i \le p
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M starts in state M_0
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        if M is in state M_p then
             record (j-p)
             M enters state M_{f(p)}
        end
    else
         M enters state M_{f(i)}
        if M is in state M_0 and T_i \neq P_{i+1} then
             j \leftarrow j + 1
        \mathbf{end}
    \mathbf{end}
end
```

Results:

The pattern P = "abaabc" occurs once in T = "aabbabaabaabca" starting at position **8**.